

# Towards Temporal Fusion Beyond the Field of View for Camera-based Semantic Scene Completion

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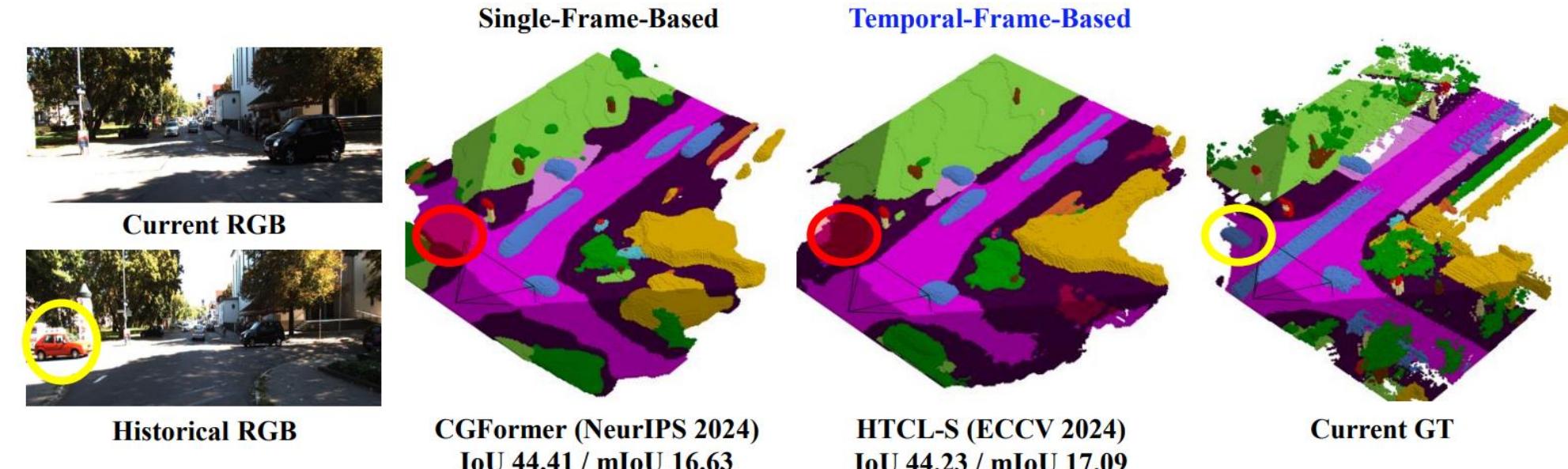
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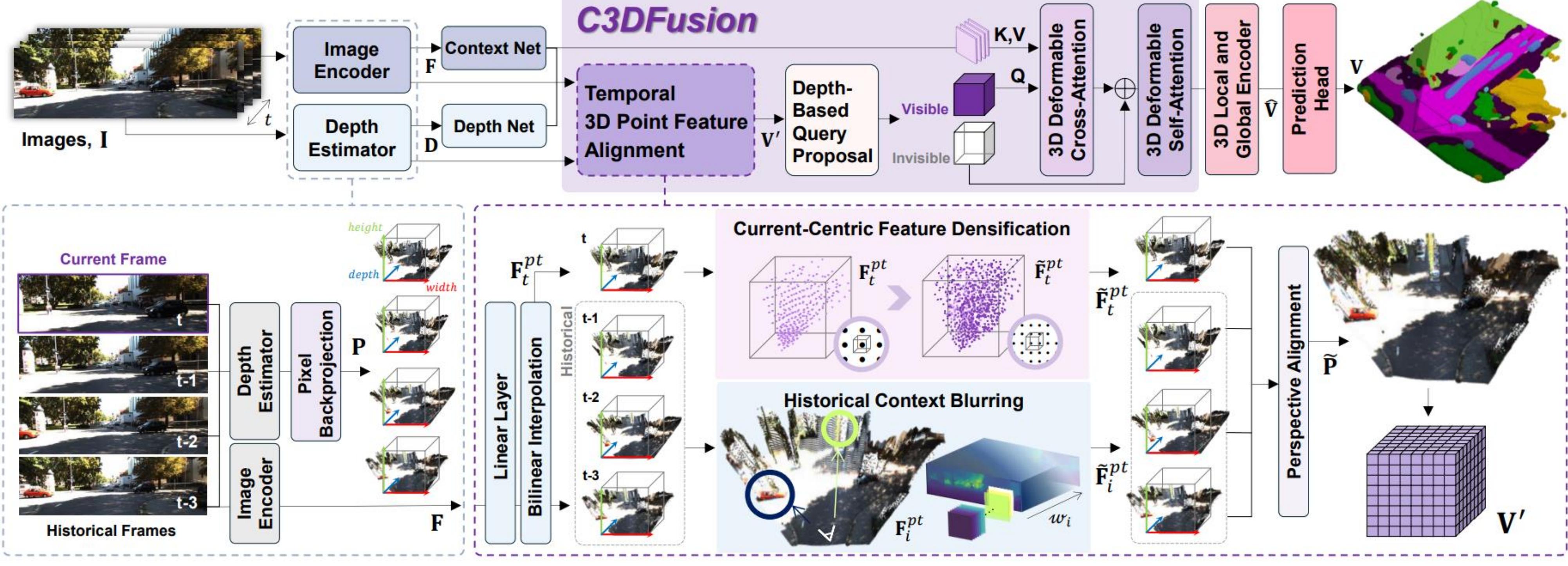
## Motivation



- Temporal fusion is widely used in camera-based 3D SSC, but improvements are mostly **limited to in-camera-view regions**.
- Out-of-camera-view blind spots** (safety-critical near the ego vehicle) remain poorly completed, even though **past frames may contain the missing context**.
- This motivates **out-of-view completion via temporal cues**, by fusing historical and current features in the current frame's 3D metric space.

## Methodology

### ✓ Overview



## Experiments

### ✓ Quantitative results on SemanticKITTI hidden test set.

Method	Input	IoU	mIoU	Single-Frame-Based																				OOV (val.)	IoU	mIoU
				road	sidewalk	parking	other-gnd.	building	car	truck	bicycle	motorcycle	other-veh.	vegetation	trunk	terrain	person	bicyclist	motorcyclist	fence	pole	sign				
MonoScene	Mono	34.16	11.08	54.70	27.10	24.80	5.70	14.40	18.80	3.30	0.50	0.70	4.40	14.90	2.40	19.50	1.00	1.40	0.40	11.10	3.30	2.10	31.07	7.02		
TPVFormer	Mono	34.25	11.26	55.10	27.20	27.40	6.50	14.80	19.20	3.70	1.00	0.50	2.30	13.90	2.60	20.40	1.10	2.40	0.30	11.00	2.90	1.50	30.76	7.87		
OccFormer	Mono	34.53	12.32	55.90	30.30	31.50	6.50	15.70	21.60	1.20	1.50	1.70	3.20	16.80	3.90	21.30	2.20	1.10	0.20	11.90	3.80	3.70	30.46	8.68		
Symphonies	Stereo	42.19	15.04	58.40	29.30	26.90	11.70	24.70	23.60	3.20	3.60	2.60	5.60	24.20	10.00	23.10	3.20	1.90	2.00	16.10	7.70	8.00	23.48	6.40		
CGFormer	Stereo	44.41	16.63	64.30	34.20	34.10	12.10	25.80	26.10	4.30	3.70	1.30	2.70	24.50	11.20	29.30	1.70	3.60	0.40	18.70	8.70	9.30	33.54	9.06		
L2C0cc-C	Stereo	44.31	17.03	66.00	35.00	33.10	13.50	25.10	27.20	3.00	3.50	3.60	4.30	25.20	11.50	30.10	1.50	2.40	0.20	20.50	9.10	8.90	32.24	8.55		
ScanSSC	Stereo	44.54	17.40	66.20	35.90	35.10	12.50	25.30	27.10	3.50	3.50	3.20	6.10	25.20	11.00	30.60	1.80	5.30	0.70	20.50	8.40	8.90	33.60	9.50		
L2C0cc-D	Stereo	45.37	18.18	<b>68.20</b>	<b>36.90</b>	34.60	<b>16.20</b>	25.80	28.30	4.50	4.90	3.30	<b>7.20</b>	26.20	11.90	32.00	2.10	2.40	0.30	21.60	<b>9.60</b>	<b>9.50</b>	31.85	10.05		
<b>Ours</b>	<b>Stereo</b>	<b>47.62</b>	<b>18.98</b>	<b>67.00</b>	<b>36.30</b>	33.20	<b>19.30</b>	<b>30.60</b>	<b>29.00</b>	3.30	<b>5.40</b>	<b>4.40</b>	4.70	<b>29.60</b>	<b>14.70</b>	<b>33.80</b>	1.60	2.80	0.30	<b>22.80</b>	<b>11.40</b>	<b>10.40</b>	<b>44.37</b>	<b>17.17</b>		

### ✓ Quantitative results on SSCBench-KITTI-360 test set.

Method	Input	IoU	mIoU	Single-Frame-Based																				OOV (test)	IoU	mIoU
				car	bicycle	motorcycle	truck	other-veh.	person	road	parking	sidewalk	other-gnd.	building	fence	vegetation	terrain	inf.-sign	other-struct.	other-obj.						
MonoScene	Mono	37.87	12.31	19.34	0.43	0.58	8.02	2.03	0.86	48.35	11.38	28.13	3.32	32.89	3.53	26.15	16.75	6.92	5.67	4.20	3.09	-	-	-		
TPVFormer	Mono	40.22	13.64	21.56	1.09	1.37	8.06	2.57	2.38	52.99	11.99	31.07	3.78	34.83	4.80	30.08	17.52	7.46	5.86	5.48	2.70	-	-	-		
OccFormer	Mono	40.27	13.81	22.58	0.66	0.26	9.89	3.82	2.77	54.30	13.44	31.53	3.55	36.42	4.80	31.00	19.51	7.77	8.51	6.95	4.60	-	-	-		
Symphonies	Stereo	44.12	18.58	30.02	1.85	5.90	<b>25.07</b>	<b>12.06</b>	<b>8.20</b>	54.94	13.83	32.76	<b>6.93</b>	35.11	8.58	38.33	11.52	14.01	9.57	<b>14.44</b>	<b>11.28</b>	34.39	11.93	44.72	15.61	
CGFormer	Stereo	48.07	20.05	29.85	3.42	3.96	17.59	6.79	6.63	<b>63.85</b>	17.15	40.72	5.53	42.73	8.22	38.80	24.94	16.24	17.45	10.18	6.77	4.47	10.30	45.09	15.44	
ScanSSC	Stereo	48.29	20.14	29.91	3.78	4.28	14.34	9.08	6.65	62.21	18.16	40.19	5.16	42.68	8.83	38.84	25.50	16.60	<b>19.14</b>	10.30	6.89	45.09	15.44	-	-	
<b>Ours</b>	<b>Stereo</b>	<b>49.28</b>	<b>21.74</b>	<b>31.16</b>	<b>5.39</b>	<b>7.01</b>	<b>18.12</b>	<b>8.25</b>	<b>5.66</b>	<b>63.70</b>	<b>19.12</b>	<b>41.64</b>	<b>5.09</b>	<b>43.93</b>	<b>10.43</b>	<b>40.73</b>	<b>27.62</b>	<b>19.30</b>	<b>23.08</b>	<b>12.34</b>	<b>8.74</b>	<b>52.41</b>	<b>23.72</b>	-	-	

### ✓ Qualitative Results

